



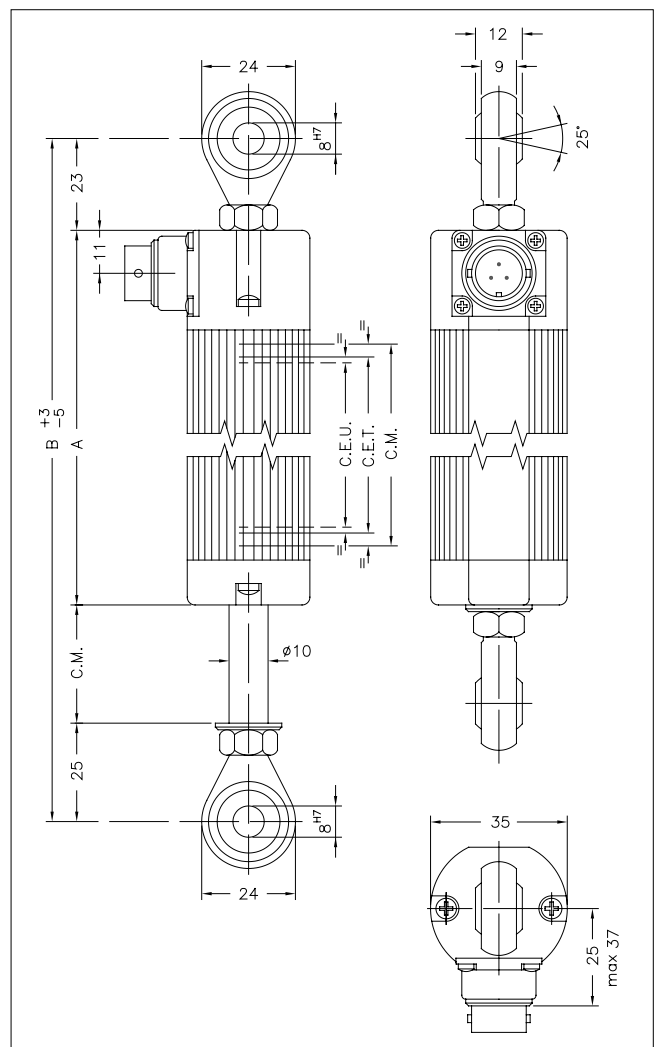
Principal characteristics

- The transducer is designed to satisfy extreme applicative demands in terms of mechanical strength.
- The 10 mm diameter rod, large steel joints, and reinforced structure make this series mechanically ideal for metalworking, woodworking, and ceramics.
- Installation is simplified by the lack of electrical signal variation at output outside theoretical electrical stroke.
- The structure based on self-aligning and weight-bearing ball joints permits assembly with free movement of the transducer axle.

TECHNICAL DATA

Useful electrical stroke (C.E.U.)	50/100/130/150/175/200/225/275/300/360/375/400/450/500/600/750
Independent linearity (within C.E.U.)	$\pm 0,05\%$
Resolution	infinite
Repeatability	0,01 mm
Protection	IP65
Displacement speed	≤ 5 m/s
Displacement force	≤ 10 N
Life	$>25 \times 10^6$ m strokes, or 100×10^6 operations, whichever is less (within C.E.U.)
Vibrations	5...2000 Hz, $A_{max} = 0,75$ mm $a_{max} = 20$ g
Shock	50 g, 11 ms.
Tolerance on resistance	$\pm 20\%$
Recommended cursor current	$< 0,1 \mu A$
Maximum cursor current	10 mA
Max. applicable voltage	60 V
Electrical isolation	$>100 M\Omega$ a 500 V~, 1 bar, 2 s
Dielectric strength	$< 100 \mu A$ a 500 V~, 50 Hz, 2 s, 1 bar
Dissipation at 40°C (0 W at 120°C)	3 W
Actual Temperature Coefficient of the output voltage	$< 1,5 ppm/^{\circ}C$
Working temperature	-30...+100°C
Storage temperature	-50...+120°C
Case material	Anodised aluminium Nylon 66 G 25
Control rod material	Stainless steel AISI 303
Fixing	2 selfloading and selfaligning ball-joints

MECHANICAL DIMENSIONS

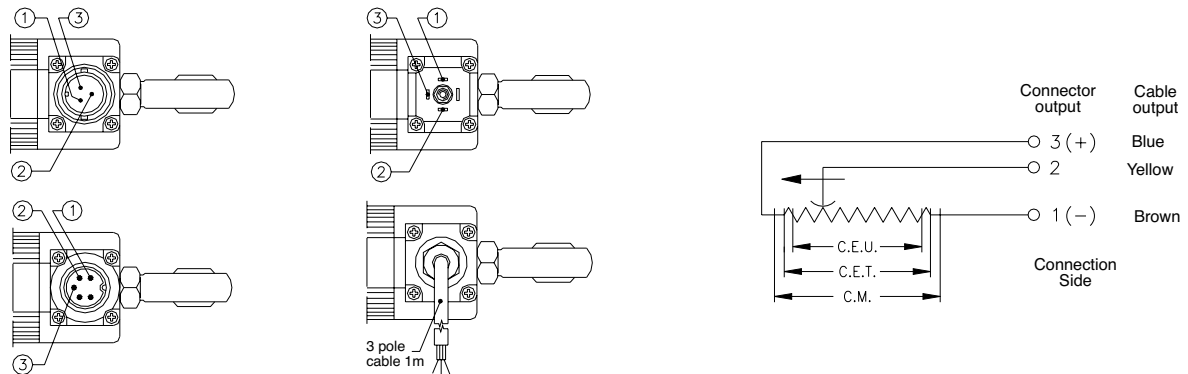


Important: all the data reported in the catalogue linearity, lifetime, temperature coefficient are valid for a sensor utilization as a ratiometric device with a max current across the cursor $I_c \leq 0.1 \mu A$.

MECHANICAL / ELECTRICAL DATA

MODEL		50	100	130	150	175	200	225	275	300	360	375	400	450	500	600	750	
Useful electrical stroke (C.E.U.) +3/-0	mm	50	100	130	150	175	200	225	275	300	360	375	400	450	500	600	750	
Theoretical electrical stroke (C.E.T.) ± 1	mm	C.E.U. + 3					C.E.U. + 4					364	380	406	457	508	609	762
Resistance (C.E.T.)	kΩ	5					5					5	5	5	5	5	5	10
Mechanical stroke (C.M.)	mm	C.E.U. + 9					C.E.U. + 10					370	386	412	463	518	619	772
Case length (A)	mm	C.E.U. + 129					C.E.U. + 130					496	512	538	589	664	765	918
Min. distance between ball-joints (B)	mm	C.E.U. + 177					C.E.U. + 178					544	560	586	637	712	813	966

ELECTRICAL CONNECTIONS



INSTALLATION INSTRUCTIONS

- Respect the indicated electrical connections (DO NOT use the transducer as a variable resistance)
- When calibrating the transducer, be careful to set the stroke so that the output does not drop below 1% or rise beyond 99% of the supply voltage.

ORDER CODE

Displacement transducer	PC																		
3-pole connector output	H																		
4-pole connector output	M																		
DIN43650 ISO4400																			
5-pole connector output	B																		
DIN45322																			
3-pole PVC cable output	F																		
3x0,25 1m																			

Model

Ex.: **PC - M - 275**

Displacement transducer model PC, 4 pole connector output
DIN43650 - ISO 4400, useful electrical stroke (C.E.U.) 275mm

OPTIONAL ACCESSORIES

4-pin 90° radial female PCM connector DIN43650 IP65 clamp PG9 for ø6 - ø8 mm wire	CON008
3-pin axial female PCH connector IP40 clamp for wire ø4 - ø6 mm	CON002
5-pin axial female PCB connector DIN43322 IP40 clamp for wire ø4 - ø6 mm	CON011
5-pin axial female PCB connector DIN43322 IP65 clamp PG7 for wire ø4 - ø6 mm	CON012
5-pin 90° radial female PCB connector DIN43322 IP40 clamp for wire ø4 - ø6 mm	CON013

GEFRAN spa reserves the right to make any kind of design or functional modification at any moment without prior notice

GEFRAN

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