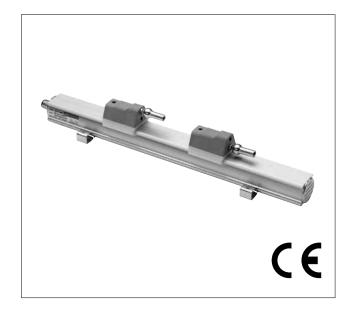
## MK4 CANopen

CONTACTLESS MAGNETOSTRICTIVE LINEAR POSITION TRANSDUCER (CANopen OUTPUT)



TECHNICAL DATA	
Model	from 50 to 4000 mm
Measurement taken	linear position and speed
Position read sampling time	from 1 to 4 ms (depending on length)
Shock test DIN IEC68T2-27	100g - 11ms - single blow
Vibration DIN IEC68T2-6	12g / 102000Hz
Sliding cursor drag force	≤ 1 N
Shift speed	≤ 10 m/s
Max. acceleration	≤ 100 m/s² shift
Resolution	5 μm (2 μm on request)
Cursor	Floating ring with integrated magnets
Rated power supply	24Vdc ± 20%
Max. power ripple	1 Vpp
Max. input	90mA max
Output signal	CAN bus digital communication
Electrical isolation	500V (D.C. power/ground)
Reverse polarity protection	YES
Overvoltage protection	Varistors on power line
Overcurrent protection	PTC (self-resettable fuse on power line)
Environmental protection	IP67
Work temperature	-30+75°C
Storage temperature	-40+100°C
Coefficient of temperature	Typical 20 ppm/°C

GEFRAN

#### Main characteristics

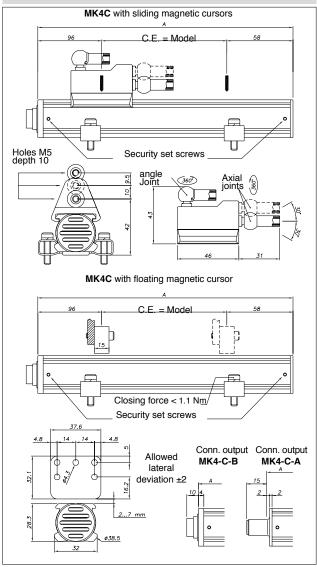
- · Absolute measurement of position and speed
- · Possibility of one or two cursors simultaneously
- Local intelligence
- Interface: CANopen DS-301 V4.01 Device Profile DS-406 V2.0
- Strokes from 50 to 4000 mm
- Position resolution up to 2µm
- Speed resolution up to 0,01mm/sec
- Linearity error 0.02%
- Repeatability error 0.01mm
- Resistance to vibrations (DIN IEC68T2/6 12g)
- IP67 protection

Contactless linear position transducer with magnetostrictive technology. The absence of electrical contact on the cursor eliminates all wear and guarantees almost unlimited life. The MK4 CANopen integrates a microprocessor to process the measurement and to diagnose the transducer.

The CAN field bus communication system provides fast and safe transmission.

The use of CANopen DS-301 protocol and Device Profile DS-406 provides quick and easy integration of the transducer in the control and automation system.

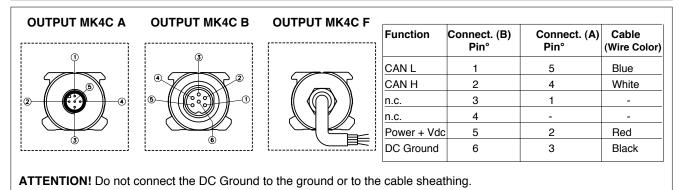
#### MECHANICAL DIMENSIONS



#### **ELECTRICAL/MECHANICAL DATA**

Model			75	10	00	130	15	0 1	175	200	2	25	25	0	300	35	50	360	40	00 4	450	50	00 5	550	60	00 6	50	700	75	80	0 85	0 9	20 8	950	1000	1100	1200	1250	1300	1400	1500
																													17	50	200	0 2	250	2500	2750	3000	325	3500	3750	4000	
Electrical stroke (C.E.)	mm																							N	loc	lel															
Independent linearity	± %F.S.		typical 0,02 (Max. 0,04)																																						
Max. dimensions (A)	mm																						N	lod	lel	+ 1	54														
Repeatability	mm																							<	: 0,	01															
Hysteresis	mm																							<	< 0,	01															

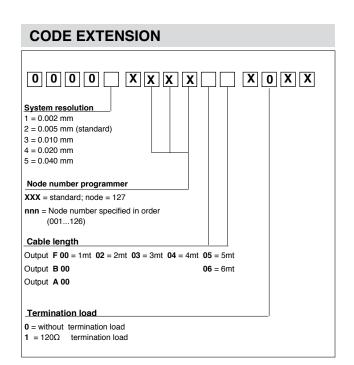
#### **ELECTRICAL CONNECTIONS**



#### **ORDER CODE**

Positi	on transc	lucer	М	K4	$\mathbf{c}$ $\Box$ $\Box$ $\Box$ $\Box$ $\Box$
CANop	en interface		С	]	
6-pin DI	N 45322 outpu	ut connector	в	]	
5-pin M connec	licro type M1 tor	2 output	A		
4-pin br (on req	aided cable uest)		F		
Model				]	
Type (s	ee table 1)			- 	
Transm (see tat	ission speed ble 2)	b			
Table 1					
Туре	N° Cursors	PD01 (St	andar	d)	PD02 (Standard)
A	1	Position 4 Speed 2 Cams 1	Byte v	vhole	Absence of data
в	2	Position 1, Speed 2 Cams 1 I	Byte w	hole	Position 2, 4 Byte whole Speed 2 Byte whole Cams 1 Byte whole
Table 2	- Transmiss	ion speed			
<b>1</b> = 1M			50 kBa	ud	7 = 50 kBaud
	) kBaud		25 kBa		8 = 20 kBaud
<b>3</b> = 500	) kBaud	6 = 10	00 kBa	ud	9 = 10 kBaud
	cal and/or el sion may be				ffering from those in the stan-

### Ex.: **MK4-C-B-0400-A-3 0000-2-XXXX-00-X-0-XX** Transducer model MK4, CANopen output, connector B, model 400, type A (one cursor), transmission speed 500 Kbaud



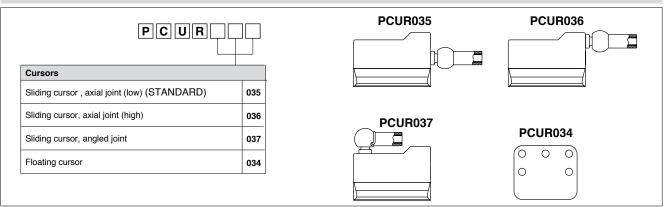
# Transmission speed as function of cable length

Cable length	Baud Rate (KBaud)	Cable length	Baud Rate (KBaud)
< 25 m	1000	< 500 m	125
< 50 m	800	< 1000 m	100
< 100 m	500	< 1250 m	50
< 250 m	250	< 2500 m	20 / 10

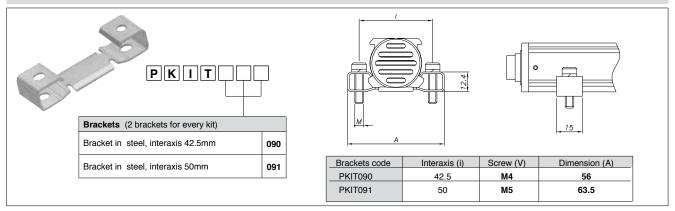
#### **Can Open Data Protocol**

SOF	Arbitration		Control	Data Field	CRC	A	C	к	EOF	Interframe Space		
1	11	1	6	0 - 8 Bytes	15	1	1	1	7	≥ 3 Bits		

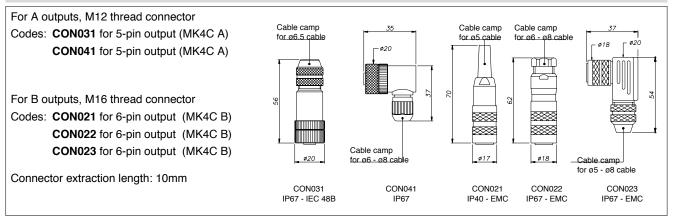
#### **CURSORS ON REQUEST**



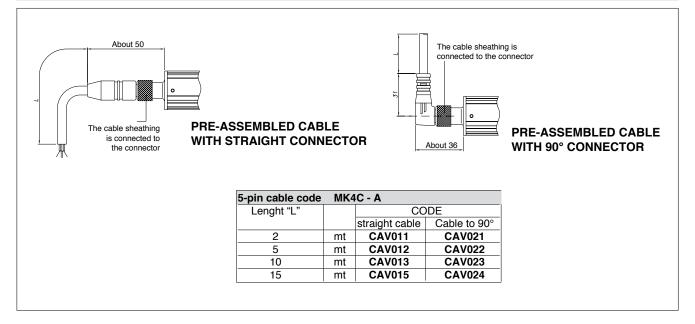
#### **BRACKET S ON REQUEST**



#### **OPTIONAL FEMALE CONNECTORS**



#### **OPTIONAL CABLES OUTPUT A**



Sensors are manufactured in compliance with:

- EMC 2004/108/CE compatibility directive

- RoHS 2002/95/CE directive

Electrical installation requirements and Conformity certificate are available on our web site: www.gefran.com

GEFRAN spa reserved the right to make aesthetic or functional changes at any time and without notice.



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